Multiresolution Kernel Approximation for Gaussian Process Regression

Yi Ding, Risi Kondor, and Jonathan Eskreis-Winkler

Motivation

- Gaussian process regression generally does not scale to beyond a few thousands data points without applying some sort of kernel approximation method.
- Most approximations focus on the high eigenvalue part of the spectrum of the kernel matrix, K, which leads to bad performance when the length scale of the kernel is small.
- We introduce Multiresolution Kernel Approximation (MKA), the first true broad bandwidth kernel approximation algorithm.
- MKA is memory efficient, and a direct method, which means that it also makes it easy to approximate K^{-1} and det(K).

Gaussian Process Regression

- Gaussian Processes (GPs) are a generalization of multivariate Gaussian distributions to the case when the underlying variables form a continuum indexed by some set \mathcal{X} .
- A GP is fully specified by its mean function $\mu(x)$, and covariance function k(x, x'), where k can be any positive semi-definite kernel.
- Given training data $\{(x_1, y_1), \ldots, (x_n, y_n)\}$, the model is $y_i = f(x_i) + \epsilon$, where $\epsilon \sim \mathcal{N}(0, \sigma^2)$ and σ^2 is a noise parameter. The posterior is also a GP with mean

 $\mu'(\boldsymbol{x}) = \mu(\boldsymbol{x}) + \boldsymbol{k}_{\boldsymbol{x}}(\boldsymbol{K} + \sigma^2 \boldsymbol{I})^{-1} \boldsymbol{y},$ where $\mathbf{k}_x = (k(x, x_1), \dots, k(x, x_n)), \mathbf{y} = (y_1, \dots, y_n), K$ is the Gram matrix or kernel matrix with elements $K_{i,i} = k(x_i, x_i), K$ and covariance

$$k'(x, x') = k(x, x') - k_{x'}(K + \sigma^2 I)^{-1} k_{x'}$$

Global Low Rank Methods

Mathematically,

$$k(x, x') pprox \sum_{s=1}^{m} \sum_{j=1}^{m} k(x, x_{i_s}) c_{i_s, i_j} k(x_{i_j}, x'),$$

Assuming that $\{x_{i_1}, \ldots, x_{i_m}\}$ is a subset of the original point set $\{x_1, \ldots, x_n\}$, amounts to an approximation of the form $K \approx K_{*,I}CK_{*,I}^{\top}$, with $I = \{i_1, \ldots, i_m\}$. The canonical choice for C is $C = W^+$, where $W = K_{I,I}$, and W^+ denotes the Moore-Penrose pseudoinverse of W. The resulting approximation

$$K \approx K_{*,I}W^+K_{*,I}^\top,$$

is known as the Nyström approximation.

Local and Hierarchical Low Rank Methods





(a) In a simple blocked low rank approximation the diagonal blocks are dense (gray), whereas the off-diagonal blocks are low rank. (b) In an HODLR matrix the low rank off-diagonal blocks form a hierarchical structure leading to a much more compact representation. (c) \mathcal{H}^2 matrices are a refinement of this idea.

Multiresolution Kernel Approximation (MKA)

MKA is a data adapted multiscale kernel matrix approximation method, which reflects the "distant clusters only interact in a low rank fashion" insight of the fast multipole method. We have the following two definitions:

- ▶ We say that a matrix H is **c-core-diagonal** if $H_{i,i} = 0$ unless either $i, j \le c$ or i = j.
- $A \approx O^{\top} H O = a^{\top} a^{\top} b$

$$P Q^{T} H Q = \underbrace{q_{1} \dots q_{L}}_{Q^{T}}$$
e-diagonal

where Q is orthogonal and H is c-core-diagonal.

Application to GPs

The direct way of applying MKA to speed up GP regression is simply using it to approximate the augmented kernel matrix $K' = (K + \sigma^2 I)$ and then inverting this approximation. Note that the resulting \tilde{K}'^{-1} never needs to be evaluated fully, in matrix form. Instead, the matrix-vector product $K'^{-1}y$ can be computed in "matrix-free" form. Assuming that the testing set $\{x_1, \ldots, x_p\}$ is known at training time, however, we can take an alternative approach, whereby instead of approximating K or K', we compute the MKA approximation of the joint train/test kernel matrix

 $\mathcal{K} = \left(rac{K \mid K_*}{K_*^\top \mid K_{\text{test}}}
ight)$ whe

Writing \mathcal{K}^{-1} in blocked form

and taking the Schur complement of D now recovers an alternative approximation $K^{-1} := A - BD^{-1}C$ to K^{-1} which is consistent with the off-diagonal block K^* leading to our final MKA–GP formula $\hat{f} = K_*^\top K^{-1} y$, where $\hat{f} = (\hat{f}(x_1), \dots, \hat{f}(x_p))^\top$. While conceptual this is somewhat more involved than naively estimating K', assuming $p \ll n$, the cost of inverting D is negligible, and the overall serial complexity of the algorithm remains $(n+p)^2$.

Simulation: 1D Toy Data

Figure 1: Snelson's 1D example: ground truth (black circles); prediction mean (solid line curves); one standard deviation in prediction uncertainty (dashed line curves).



A **c–core-diagonal compression** of a symmetric matrix $A \in \mathbb{R}^{m \times m}$ is an approximation of the form

$$H\underbrace{q_{L}\ldots q_{1}}_{Q}=(\blacksquare)(\blacksquare)(\blacksquare),$$

$$egin{aligned} & extsf{K}_{i,j} = extsf{k}(extsf{x}_i, extsf{x}_j) + \sigma^2 \ & extsf{ere} \, [extsf{K}_*]_{i,j} = extsf{k}(extsf{x}_i, extsf{x}_j') \ & [extsf{K}_{ extsf{test}}]_{i,j} = extsf{k}(extsf{x}_i, extsf{x}_j'). \end{aligned}$$

$$\left(\begin{array}{c|c} A & B \\ \hline C & D \end{array}\right)$$

Experiments on Real Data

	Та	able 1: Regress	ion Results with	h k to be $# pset$	udo-inputs/ <i>d</i> _{core}	: SMSE(MNLP)
Method	k	Full	SOR	FITC	PITC	MEKA	MKA
housing	16	0.36(-0.32)	0.93(-0.03)	0.91(-0.04)	0.96(-0.02)	0.85(-0.08)	0.52(-0.32)
rupture	16	0.17(-0.89)	0.94(-0.04)	0.96(-0.04)	0.93(-0.05)	0.46(-0.18)	0.32(-0.54)
wine	32	0.59(-0.33)	0.86(-0.07)	0.84(-0.03)	0.87(-0.07)	0.97(-0.12)	0.70(-0.23)
pageblocks	32	0.44(-1.10)	0.86(-0.57)	0.81(-0.78)	0.86(-0.72)	0.96(-0.10)	0.63(-0.85)
compAct	32	0.58(-0.66)	0.88(-0.13)	0.91(-0.08)	0.88(-0.14)	0.75(-0.21)	0.60(-0.32)
pendigit	64	0.15(-0.73)	0.65(-0.19)	0.70(-0.17)	0.71(-0.17)	0.53(-0.29)	0.30(-0.42)

Figure 2: SMSE and MNLP as a function of the number of pseudo-inputs/ d_{core} on two datasets. In the given range MKA clearly outperforms the other methods in both error measures.



Across the range of pseudo-inputs/ d_{core} size considered, MKA's performance is robust to d_{core} , while low-rank based methods' performance changes rapidly, which shows MKA's ability to achieve good regression results even with a crucial compression level.

Conclusions

- of the kernel matrix.
- computational bottlenecks in GP problems.



NIPS 2017, Long Beach, CA, USA

Whether a learning problem is low rank or not depends on the nature of the data rather than just the spectral properties

MKA allows fast direct calculations of the inverse of the kernel matrix and its determinant, which are almost always the