

# Discrete Math 37110 - Class 17 (2016-11-22)

Instructor: László Babai  
Notes taken by Jacob Burroughs  
Revised by instructor

## 17.1 Determinant, trace

**DO 17.1.**  $\det(AB) = \det(A) \det(B)$

Define  $\text{trace}(A) = \sum a_{ii}$  = the sum of diagonal elements

**DO 17.2.**  $\text{trace}(A + B) = \text{trace}(A) + \text{trace}(B)$

**DO 17.3.** If  $A \in \mathbb{R}^{k \times \ell}$  and  $B \in \mathbb{R}^{\ell \times k}$  then  $\text{trace}(AB) = \text{trace}(BA)$

## 17.2 Complex numbers

We use the symbol  $i$  with the rule  $i^2 = -1$ . We write the vector  $(a, b) \in \mathbb{R}^2$  as  $z = a + bi$  and call it a “complex number.” So  $\mathbb{C} = \{z = a + bi \mid a, b \in \mathbb{R}\}$  is the set of complex numbers. We define addition and multiplication of complex numbers. Addition is componentwise, as we add vectors in  $\mathbb{R}^2$ ; multiplication is defined using the rule  $i^2 = -1$ :

- (a)  $z_1 + z_2 = (a_1 + a_2) + (b_1 + b_2)i$
- (b)  $z_1 \cdot z_2 = (a_1b_1 - a_2b_2) + (a_1b_2 + a_2b_1)i$

If  $b = 0$  we say  $z$  is real. If  $a = 0$  we say  $z$  is imaginary.

The **complex conjugate** of  $z$  is  $\bar{z} = a - bi$ .

$a$  is the “real part”:  $a = (z + \bar{z})/2$  and  $b$  is the “imaginary part”:  $b = (z - \bar{z})/(2i)$

$$z \cdot \bar{z} = a^2 + b^2 = |z|^2$$

**Theorem 17.4.** If  $z \neq 0$ , then  $\exists \frac{1}{z}$

*Proof.*

$$\frac{1}{z} = \frac{\bar{z}}{|z|^2}$$

□

The form  $a + bi$  is called the **canonical form** of a complex number. The **polar form** of a complex number is

$$z = r(\cos(\theta) + i \sin(\theta))$$

Here  $r = |z|$  is the absolute value and the angle  $\theta$  is the **argument**. The argument  $\theta$  is unique modulo  $2\pi$ .

We obtain the polar form as follows. We observe that  $|z_0| = 1$  where  $z_0 = z/|z|$ . Therefore  $z = |z| \cdot z_0 = |z|(\cos \theta + i \sin \theta)$ .

**DO 17.5.**  $\arg(z_1 z_2) = \arg(z_1) + \arg(z_2)$  and then  $\arg(z^n) = n \arg z$

**DO 17.6.**  $\cos(\alpha + \beta) + i \sin(\alpha + \beta) = (\cos \alpha + i \sin \alpha)(\cos \beta + i \sin \beta)$

**DO 17.7** (Euler). We note that  $\cos \alpha + i \sin \alpha$  can be written as  $e^{i\alpha}$ . (Hint: power series.)

**DO 17.8.** The solutions to  $z^n = 1$  are called the “complex  $n$ -th roots of unity.” Prove: they are  $\cos(\frac{2k\pi}{n}) + i \sin(\frac{2k\pi}{n})$  for  $k = 0, 1, \dots, n-1$ .

**Theorem 17.9** (Fundamental Theorem of Algebra). *If  $f = a_0 + a_1 t + \dots + a_n t^n \in \mathbb{C}[t]$  where  $a_n \neq 0$  then  $(\exists \alpha_1, \dots, \alpha_n \in \mathbb{C})(f(t) = a_n \prod_{j=1}^n (t - \alpha_j))$*

The **multiplicity** of a root is the power to which the corresponding term is raised in the factorization. The sum of the multiplicities is  $n$ .

**DO 17.10.**  $f$  has no multiple roots if and only if  $\gcd(f, f') = 1$

### 17.3 Fields

**Definition 17.11.** A field  $\mathbb{F}$  is a set with two operations  $+, \times$  such that

1.  $(\mathbb{F}, +)$  is an abelian group.
2.  $(\mathbb{F}^\times, \times)$  is an abelian group, where  $\mathbb{F}^\times = \mathbb{F} \setminus \{0\}$ .
3.  $a(b + c) = ab + ac$

**DO 17.12.** In a field,  $ab = 0$  if and only if  $a = 0$  or  $b = 0$

Some examples of fields are  $\mathbb{R}$  (real numbers),  $\mathbb{C}$  (complex numbers),  $\mathbb{Q}$  (rational numbers),  $\mathbb{F}_p$  ( $p$  prime): the residue classes modulo  $p$ . The set of integers,  $\mathbb{Z}$  does not form a field.

**DO 17.13.** The set of residue classes modulo  $m$  forms a field if and only if  $m$  is a prime. (Hint: you will need to use the prime property.)

Henceforth  $\mathbb{F}$  denotes any field, but most of the time you can think of  $\mathbb{F}$  being  $\mathbb{R}$  or  $\mathbb{C}$ .

### 17.4 Basis, rank, dimension. First miracle

In this section  $V$  is a vector space over a field  $\mathbb{F}$ , i.e.,  $\mathbb{F}$  is the set of scalars.

**Definition 17.14.** Let  $B$  be a list of elements of  $V$ . We say that  $B$  is a *basis* of  $V$  if  $B$  is linearly independent and  $B$  spans  $V$ .

**DO 17.15.**  $B$  is a basis if and only if each  $v \in V$  is a unique linear combination of  $B$ . So if  $B = (b_1, \dots, b_n)$  then  $(\forall v \in V)(\exists! \alpha_1, \dots, \alpha_n \in \mathbb{F})(v = \sum_{i=1}^n \alpha_i b_i)$ . — The coefficients  $\alpha_i$  are called the **coordinates** of  $v$  wrt  $B$ . (wrt = “with respect to”)

**DO 17.16.**  $B$  is a basis if and only if it is a maximal linearly independent set.

To prove this, use the following exercise.

**DO 17.17.** If  $b_1, \dots, b_k$  are linearly independent and  $b_1, \dots, b_k, c$  are linearly dependent, then  $c \in \text{span}(b_1, \dots, b_k)$

**DO 17.18.** Every vector space has a basis. Hint: This is immediate from Exercise 17.16 if the size of linear independent sets in  $V$  is bounded. Otherwise it follows from Zorn's lemma (set theory).

**Theorem 17.19** (1st miracle of linear algebra). *If  $v_1, \dots, v_k$  are linearly independent,  $w_1, \dots, w_\ell$  are any vectors and  $v_1, \dots, v_k \in \text{span}(w_1, \dots, w_\ell)$  then  $k \leq \ell$*

**DO 17.20.** Study proof of the above

**DO 17.21.**  $\dim \mathbb{F}^n = n$  (equivalent to 1st miracle if  $\dim$  defined as max number of lin indep vectors)

The **rank** of a set  $S$  of vectors is the maximum number of linearly independent vectors from  $S$

## 17.5 Rank of a matrix

The **column-rank** of  $A$  is the rank of the set of columns

The **column-space** of  $A$  is the span of the columns

**DO 17.22.** The column-rank is the dimension of the column-space. (This is also equivalent to the First Miracle.)

**DO 17.23.** A basis of  $F[t]$  is  $\{1, t, t^2, t^3, \dots\}$

**DO 17.24.** Show that the column-rank of  $A + B \leq \text{column-rank of } A + \text{column-rank of } B$

**DO 17.25.** Elementary column operations do not change column-rank

**DO 17.26.** Elementary row operations do not change column-rank

**DO 17.27.** Starting from any matrix, through a sequence of elementary row and column operations we can obtain a matrix that has at most one non-zero entry in each row and in each column.

**DO 17.28.** Prove: if a matrix has at most one non-zero entry in each row and in each column then its column-rank is equal to the number of non-zero entries and the row-rank is also equal to the number of non-zero entries.

**Theorem 17.29** (2nd miracle of linear algebra). *The column-rank of  $A$  is equal to the row-rank of  $A$*

**DO 17.30.** Prove this theorem. (Hint: combine the preceding four exercises.)

*Proof.* Use column and row-operations until there is at most one nonzero entry in each row and column. Let  $r$  be the number of nonzero entries remaining. Then both the row-rank and the column-rank are equal to  $r$ . Now use exercises 17.25 and 17.26.  $\square$

**Definition 17.31.** The rank of  $A$  is the column-rank/row-rank

**DO 17.32.**  $\text{rk}(A) = \text{rk}(A^T)$

## 17.6 Systems of linear equations

A system of  $k$  linear equations in  $n$  unknowns can be written as a matrix equation  $Ax = b$  where  $A \in \mathbb{F}^{k \times n}$ ,  $b \in \mathbb{F}^k$  and  $x \in \mathbb{F}^n$ .

**DO 17.33.**  $Ax = b$  is solvable if and only if the rank of  $A$  = the rank of the  $k \times (n + 1)$  matrix  $[A \mid b]$ . (Hint: use the next exercise.)

**DO 17.34.** If the columns of  $A \in \mathbb{F}^{k \times n}$  are  $a_1, \dots, a_n$  and  $x = (x_1, \dots, x_n)^n$  then  $Ax = x_1 a_1 + \dots + x_n a_n$ . So the column space of  $A$  is  $\{Ax \mid x \in \mathbb{R}^n\}$ .

**Homogeneous system of linear equations:** where  $b = 0$  — always has trivial solution  $x = 0$ .

Want to find  $U = \{x \mid Ax = 0\} \subseteq \mathbb{F}^n$  (the set of solutions)

**DO 17.35.** Prove  $U \leq \mathbb{F}^n$ . The dimension of  $U$  is called the **nullity** of  $A$ .

**DO 17.36.** Rank-nullity theorem:  $\dim(U) + \text{rk}(A) = n$

**DO 17.37.** There exists a non-trivial solution to  $A \in M_n(\mathbb{F})$  if and only if  $\text{rk}(A) < n$

**Theorem 17.38.** The following statements are equivalent for  $A \in M_n(\mathbb{F})$

(a)  $\text{rk}(A) = n$

(b)  $Ax = 0$  has no no-trivial solutions

(c)  $\exists A^{-1}$  such that  $A^{-1}A = AA^{-1} = I$

(d)  $\det(A) \neq 0$

If either of these conditions (and therefore all of them) hold then we call  $A$  “non-singular”

## 17.7 Eigenvalues, characteristic polynomial

**Theorem 17.39.**  $\lambda \in \mathbb{F}$  is an eigenvalue of  $A \in M_n(\mathbb{F})$  if and only if  $\det(\lambda I - A) = 0$

**DO 17.40.** A polynomial of degree  $n$  with a lead coefficient of 1 is called **monic**.

**Definition 17.41.** The **characteristic polynomial** of  $A \in M_n(\mathbb{F})$  is  $f_A(t) = \det(tI - A)$

**DO 17.42.** (a) The characteristic polynomial of  $A \in M_n(\mathbb{F})$  is a monic polynomial of degree  $n$ . (b) Let  $f_A(t) = a_0 + a_1t + \cdots + a_nt^n$ . Then  $a_n = 1$  (monic),  $a_{n-1} = -\text{trace}(A)$ , and  $a_0 = (-1)^n \det(A)$ .

**Theorem 17.43.** The eigenvalues of  $A$  are precisely the roots of its characteristic polynomial

**Corollary 17.44.**  $A \in M_n(\mathbb{F})$  has at most  $n$  eigenvalues.

**HW 17.45.** Find the eigenvalues in  $\mathbb{C}$  of the rotation matrix:

$$R_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

Also find the corresponding eigenvectors in  $\mathbb{C}^2$

**DO 17.46.** Prove: the  $x \mapsto R_\theta x$  transformation rotates  $\mathbb{R}^2$  by  $\theta$ .

**Definition 17.47.** An **eigenbasis** of  $A$  is a basis of  $\mathbb{F}^n$  consisting of eigenvectors of  $A$ .

**HW 17.48.**  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  has no eigenbasis over  $\mathbb{R}$  or  $\mathbb{C}$

## 17.8 Standard dot product, orthogonality, Spectral Theorem

**Definition 17.49.** For  $a, b \in \mathbb{R}^n$  we write  $a \cdot b = a^T b = \sum_{i=1}^n a_i b_i$ , the standard dot product. We call  $a, b$  **orthogonal** if  $a \cdot b = 0$ . The **norm** of the vector  $a$  is  $\|a\| = \sqrt{\sum_{i=1}^n a_i^2}$ . A list of vectors,  $v_1, \dots, v_k \in \mathbb{R}^n$ , is *orthogonal* if they are pairwise orthogonal. It is *orthonormal* if in addition  $\|v_i\| = 1$ . So  $v_1, \dots, v_k$  are orthonormal exactly if  $v_i v_j = \delta_{ij}$  (Kronecker delta). ( $\delta_{ij}$  are the entries of the identity matrix.)

**Theorem 17.50** (Spectral Theorem). If  $A \in M_n(\mathbb{R})$  and  $A = A^T$ , then  $A$  has an orthonormal eigenbasis

**HW 17.51.** Find the orthonormal eigenbasis of  $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$  and find the corresponding eigenvalues.